Validation Report

New Mexico, SPS-5 Task Order 25, CLIN 2 August 18 to 19, 2008

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1 Executive Summary

A visit was made to the New Mexico 0500 on August 18 to 19, 2008 for the purposes of conducting a validation of the WIM system located on Interstate 10 at milepost 50.2. The SPS-5 is located in the righthand, eastbound lane of a four-lane divided facility. The posted speed limit at this location is 75 mph. The LTPP lane is the only lane that is instrumented at this site. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This is a sensor relocation at the original site. The new sensors are upstream of the location visited for the site assessment by the Phase I contractor. This is the first validation visit to this location. The site was installed April 3 to 30, 2008 by International Road Dynamics Inc. The installation calibration was performed on May 15, 2008.

This site demonstrates the ability to produce research quality loading data under the observed conditions. The classification data is also of research quality for Traffic Monitoring Guide Classes based on the validation results. However, the post visit download data indicates an unacceptable percentage of unclassified and unknown vehicles.

The site is instrumented with quartz piezo WIM and iSINC electronics. It is installed in asphalt concrete.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 76,290 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 66,770 lbs., the "partial 1" truck.
- 3) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandemand an air suspension loaded to 57,920 lbs., the "partial 2" truck.

The validation speeds ranged from 61 to 75 miles per hour. The pavement temperatures ranged from 80 to 127 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was also achieved.

Table 1-1 Post-Validation results – 350500 – 19-Aug-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.3 \pm 4.5\%$	Pass
Tandem axles	±15 percent	$-0.3 \pm 7.3\%$	Pass
GVW	±10 percent	$-0.2 \pm 5.1\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: bko

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area. No profile data is provided from which WIMIndex values can be calculated. When profile data becomes available WIMIndex values will be computed and an amended report submitted.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: bko Checked:jrn

This site needs five years of data to meet the goal of five years of research quality data.

2 Corrective Actions Recommended

The right side of the trailing sensor is operating properly, but electronic measurements indicate low capacitance values. Attention should be paid to drift in left/right wheel load comparisons. Additionally this sensor should be carefully evaluated on each maintenance visit.

The post-validation download of records for August 28, 2008 had 2.6 percent unknown and unclassified vehicles. This clearly exceeds the 2 percent threshold for research quality classification data. The unclassifeds should be investigated and the necessary algorithm modifications considered.

3 Post Calibration Analysis

This final analysis is based on test runs conducted August 19, 2008 mid-morning and mid-afternoon at test site 350500 on Interstate 10. This SPS-5 site is at milepost 50.2 on the eastbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The three trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 76,290 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 66,770 lbs., the "partial 1" truck.
- 3. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 57,920 lbs., the "partial 2" truck.

Each truck made a total of 14 passes over the WIM scale at speeds ranging from approximately 61 to 75 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 80 to 127 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was also achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

The results of the validation left the equipment reporting essentially unbiased estimates for the observed validation conditions.

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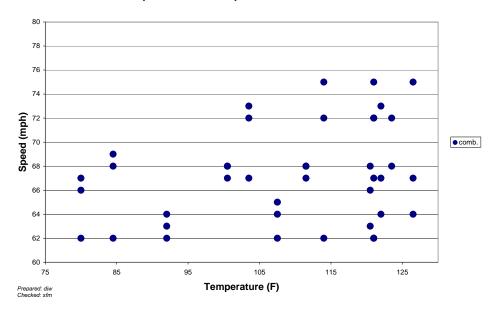
Table 3-1 Post-Validation Results – 350500 – 19-Aug-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.3 \pm 4.5\%$	Pass
Tandem axles	±15 percent	$-0.3 \pm 7.3\%$	Pass
GVW	±10 percent	$-0.2 \pm 5.1\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass
_		Prepared: bko	Checked:jrn

The validation period stretched from mid-morning to mid-afternoon resulting in a range of temperatures. The runs were conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and three temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was nearly achieved for this set of validation runs. There was a lack of low temperature; high speed runs due to the length of the turn-around time and the rate of temperature rise.

The three speed groups were divided as follows: Low speed -61 to 65 mph, Medium speed -66 to 70 mph and High speed -71 + mph. The three temperature groups were created by splitting the runs between those at 80 to 100 degrees Fahrenheit for Low temperature, 101 to 114 degrees Fahrenheit for Medium temperature and 115 to 127 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations



 $Figure \ 3-1 \ Post-Validation \ Speed-Temperature \ Distribution - 350500 - 19-Aug-2008$

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. While the overall results indicate unbiased estimates, the low speed group indicates some degree of underestimation. It would appear that the factor adjustments based on the calibration did not have similar impacts on each speed bin. This speed range is about the 35th percentile.

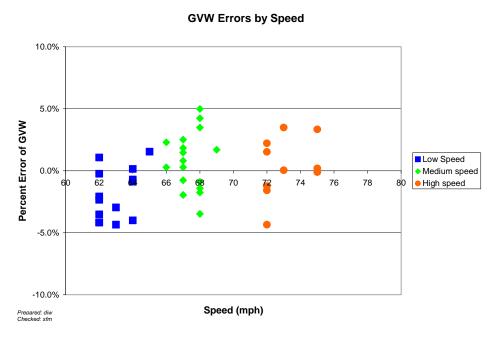


Figure 3-2 Post-validation GVW Percent Error vs. Speed – 350500 – 19-Aug-2008

Figure 3-3 shows the relationship between temperature and GVW percentage error. There is no apparent trend in GVW error with temperature.

GVW Errors by Temperature

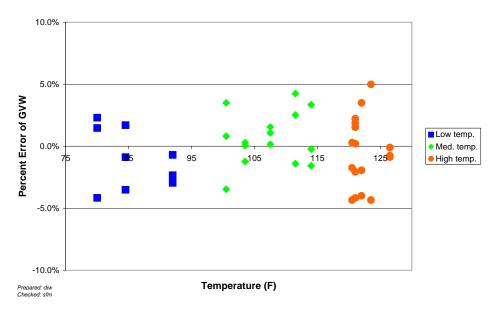


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 350500 - 19-Aug-2008

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. There is no apparent relation between speed and spacing error.

Drive Tandem Spacing vs. WIM Speed

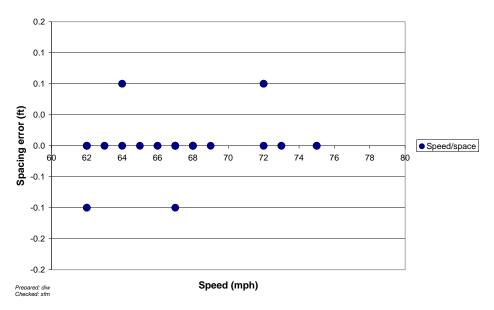


Figure 3-4 Post-Validation Spacing vs. Speed – 350500 – 19-Aug-2008

3.1 Temperature-based Analysis

The three temperature groups were created by splitting the runs between those at 80 to 100 degrees Fahrenheit for Low temperature, 101 to 114 degrees Fahrenheit for Medium temperature and 115 to 127 degrees Fahrenheit for High temperature.

Table 3-2 Post-Validation Results by Temperature Bin – 350500 – 19-Aug-2008

Element	95% Limit	Low Temperature 80 to 100 °F	Medium Temperature 101 to 114 °F	High Temperature 115 to 127 °F
Steering axles	<u>+</u> 20 %	$1.7 \pm 6.8\%$	$0.5 \pm 2.7\%$	$-0.6 \pm 4.7\%$
Tandem axles	<u>+</u> 15 %	$-1.5 \pm 6.1\%$	$0.6 \pm 6.7\%$	$-0.5 \pm 8.6\%$
GVW	<u>+</u> 10 %	$-1.0 \pm 5.5\%$	$0.6 \pm 4.6\%$	$-0.6 \pm 5.9\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

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Table 3-2 indicates that at low temperatures loading statistics are generally underestimated. The loading statistics at medium temperature tend to be overestimated. The variability is similar for all temperatures for GVW errors.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph. There are no apparent differences in truck responses with temperature.

GVW Errors vs. Temperature by Truck

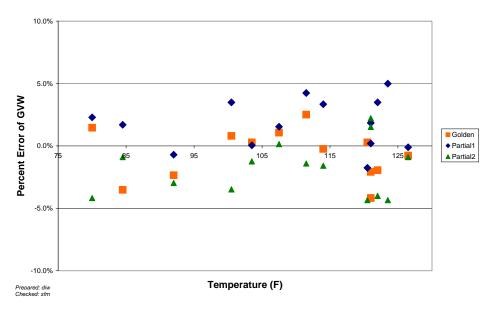


Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 350500 – 19-Aug-2008

Figure 3-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are

associated only with Class 9 vehicles. Steering axle's errors trend downward with increasing temperature.

10.0% 5.0% 10.0% 75 85 95 105 115 125 Low temp. Med. temp. High temp.

Steering Axle Errors vs. Temperature

Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group -350500 -19-Aug-2008

Temperature (F)

3.2 Speed-based Analysis

The three speed groups were created using 61 to 65 mph for Low speed, 66 to 70 mph for Medium speed and 71+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 350500 – 19-Aug-2008

Element	95% Limit	Low Speed 61 to 65 mph	Medium Speed 66 to 70 mph	High Speed 71+ mph
Steering axles	<u>+</u> 20 %	$-0.2 \pm 4.1\%$	$0.6 \pm 5.6\%$	$0.4 \pm 4.8\%$
Tandem axles	<u>+</u> 15 %	$-2.2 \pm 5.6\%$	$0.8 \pm 6.3\%$	$0.5 \pm 9.9\%$
GVW	<u>+</u> 10 %	$-1.9 \pm 4.4\%$	$0.8 \pm 4.9\%$	$0.4 \pm 5.5\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Table 3-3 indicates very little difference in the errors of estimates with speed for medium and high speed. The low speed group however tends to have underestimates of all loading statistics.

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Figure 3-7 illustrates the trends with speed by truck. The golden truck (squares) only ran at low and medium speed due to a speed governor on the engine. The golden truck exhibited an upward trend in error estimates with increasing speed. The partial 1 (diamonds) and partial 2 (triangles) trucks show little if any tendency for a trend in GVW

-10.0%

errors with increasing speed. The partial 1 truck (diamonds) tended to overestimate at all speeds. The partial 2 truck (triangles) tended to underestimate at all speeds. This divergence in estimates contributed to the overall scatter observed.

GVW Errors vs. Speed

10.0% 5.0% 60 62 64 66 68 70 72 74 76 78 80 -5.0%

Figure 3-7 Post-Validation GVW Percent Error vs. Speed by Truck-350500-19-Aug-2008

Speed (mph)

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. There is no apparent trend in steering axle error with speed.

Steering Axle Errors vs. Speed

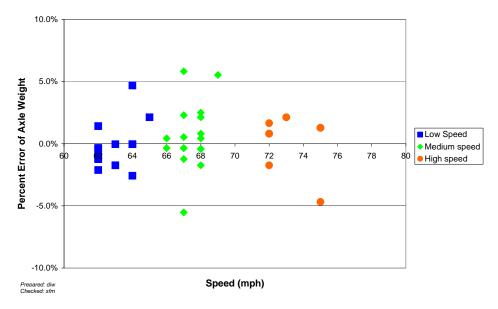


Figure 3-8 Post-Validation Steering Axle Percent Error vs. Speed by Group – 350500 – 19-Aug-2008

3.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles. Classification 14 has been added to define unknown vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles. This is not however consistent with data downloaded after the validation was complete.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The large values for Classes 5 and 8 are a reflection of the small number observed in the validation sample. The overall misclassification rate is 2.0 percent.

Table 3-4 Truck Misclassification Percentages for 350500 – 19-Aug-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	N/A	5	50	6	N/A
7	N/A				
8	33	9	0	10	N/A
11	0	12	0	13	N/A

Prepared: bko Checked:jrn

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero. There were less than five Class 5 and Class 8 vehicles observed. The mean difference reflects the equipment reporting Class 5 vehicles as Class 8 vehicles.

Table 3-5 Truck Classification Mean Differences for 350500 – 19-Aug-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	N/A	5	- 50	6	N/A
7	N/A				
8	50	9	0	10	N/A
11	0	12	0	13	N/A

Prepared: bko Checked:jrn

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. The observed bias and variability are thought to be more strongly related to radar speed precision than errors in the WIM equipment.

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

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4 Pavement Discussion

The pavement condition did not appear to influence truck movement across the sensors.

4.1 Profile Analysis

Profile data collected since the site installation do not exist. An amended report will be submitted when the data is available.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement no distresses that would influence truck movement across the WIM scales were noted. The prior sensor installation downstream did not appear to influence truck movement.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires and any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes quartz piezo WIM sensors and iSINC electronics. The sensors are installed in an asphalt concrete pavement.

Between the installation of the site and the beginning of the validation the pavement sank around the WIM sensors. This produced a bump in the pavement that required grinding the WIM sensors to make them once again flush with the pavement surface.



Photo 5-1 Results of Grinding Leading WIM Sensor - 350500 - 18-Aug-2008

The grinding was done along the entire width of the lane for both sensors. Photo 5-1 shows the aftermath of grinding the leading WIM sensor. Traffic has dispersed the dust left after grinding from the wheelpath. Photo 5-2 shows the results of the same activity for the trailing sensor. This photograph shows that the grinding extends into the edge line for the shoulder.



Photo 5-2 Grinding of Trailing Center at Shoulder - 350500 - 18-Aug-2008

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. All sensors except the right side trailing sensor and system components were found to be within operating parameters.

The right side of the trailing sensor is operating but electronic measurements indicate low capacitance values. Attention should be paid to drift in left/right wheel load comparisons.

5.2 Calibration Process

The equipment required one-iteration of the calibration process between the initial 40 runs and the final 40 runs. The calibration was undertaken to remove the observed underestimation of loading statistics.

The operating system weight compensation parameters that were in place prior to the Pre-Validation as a result of installation calibration are in Table 5-1.

Table 5-1 Initial System Parameters - 350500 - 18-Aug-2008

Speed Bin	Sensor 1	Sensor 2
88 kph	3760	2997
96 kph	3691	2942
105 kph	3549	2829
112 kph	3694	2944
120 kph	3623	2888

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5.2.1 Calibration Iteration 1

As a result of the Pre-Validation, where loading statistics where consistently underestimated, the compensation factors were adjusted as shown in Table 5-2.

Table 5-2 Calibration 1 - Change in Parameters - 350500 - 19-Aug-2008

Speed Bins	Sensor 1	Change	Sensor 2	Change
88 kph	3760		2997	
96 kph	3691		2942	
105 kph	3742	5.4%	2982	5.4%
112 kph	3816	3.3%	3041	3.3%
120 kph	3788	4.5%	3019	4.5%

Prepared: bko Checked:jrn

The outcome of the calibration runs after factor adjustment is shown in Table 5-3. The improvement in the estimates particularly at the medium and high speeds as shown in Figure 5-1 was considered sufficient to end calibration iterations.

Table 5-3 Calibration Iteration 1 Results – 350500 – 19-Aug-2008 (08:25 AM)

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$0.1 \pm 5.1\%$	Pass
Tandem axles	±15 percent	$-1.3 \pm 6.6\%$	Pass
GVW	±10 percent	-1.1 ± 4.9%	Pass
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	Pass

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GVW Errors by Speed

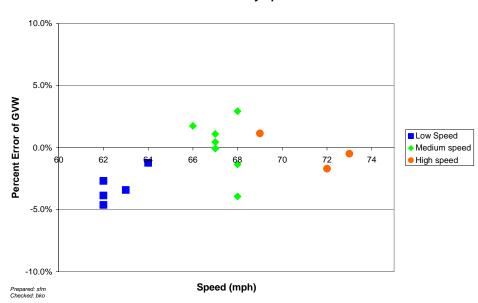


Figure 5-1 Calibration Iteration 1 GVW Percent Error vs. Speed Group – 350500 – 19-Aug-2008 (08:25 AM)

5.3 Summary of Traffic Sheet 16s

This site has no prior validation information, and only the current visit is shown in the tables below. Table 5-4 has the information for TRF_CALIBRATION_AVC for Sheet 16s submitted for this validation. The Sheet 16s available reflect only this contractor's validation visit. The Sheet 16 for the assessment applies to a different sensor installation and is not included here.

Table 5-4 Classification Validation History – 350500 – 19-Aug-2008

Date	Method	Mean Difference				Percent
		Class 9	Class 8	Other 1	Other 2	Unclassified
19-Aug-2008	Manual	0	50			0.0
18-Aug-2008	Manual	0	100			0.0

Prepared: bko Checked:jrn

Table 5-5 has the information for TRF_CALIBRATION_WIM for Sheet 16s submitted for this validation. The Sheet 16s available reflect only this contractor's validation visits.

Table 5-5 Weight Validation History – 350500 – 19-Aug-2008

Date	Method	Mean Error and (SD)		
		GVW	Single Axles	Tandem Axles
19-Aug-2008	Test Trucks	-0.2 (2.5)	0.3 (2.3)	-0.3 (3.7)
18-Aug-2008	Test Trucks	-4.3 (2.3)	-2.1 (2.3)	-4.7 (3.1)

5.4 Projected Maintenance/Replacement Requirements

The right side of the trailing sensor is operating but electronic measurements indicate low capacitance values. Attention should be paid to drift in left/right wheel load comparisons. Additionally this sensor should be carefully evaluated on each maintenance visit.

This site is scheduled for semi-annual maintenance under the installation contract.

6 Pre-Validation Analysis

This pre-validation analysis is based on test runs conducted August 18, 2008 from late morning to late afternoon at test site 350500 on Interstate 10. This SPS-5 site is at milepost 50.2 on the eastbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The three trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 76,800 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 66,440 lbs., the "partial 1" truck.
- 3. 5-axle tractor semi-trailer with a tractor having a an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 57,400 lbs., "partial 2" truck.

For the initial validation each truck made a total of 14 passes over the WIM scale at speeds ranging from approximately 61 to 75 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 93 to 127 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was also achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

Table 6-1 indicates that the various loading statistics are underestimated. The GVW is sufficiently underestimated that a slight increase in underestimation or variability would result in a failure of the site.

Table 6-1 Pre-Validation Results – 350500 – 18-Aug-2008

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-2.1 \pm 4.6\%$	Pass
Tandem axles	±15 percent	$-4.7 \pm 6.2\%$	Pass
GVW	±10 percent	$-4.3 \pm 4.6\%$	Pass
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

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The runs were conducted from late morning through the late afternoon. The runs were conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and two temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was nearly achieved for this set of validation runs. A midday break resulted in a gap in temperatures that resulted in only two temperature groups for evaluation rather than the three the range would suggest.

The three speed groups were divided into 61 to 65 mph for Low speed, 66 to 70 mph for Medium speed and 71+ mph for High speed. The two temperature groups were created by splitting the runs between those at 93 to 110 degrees Fahrenheit for Low temperature, and 111 to 127 degrees Fahrenheit for High temperature.

Speed versus Temperature Combinations

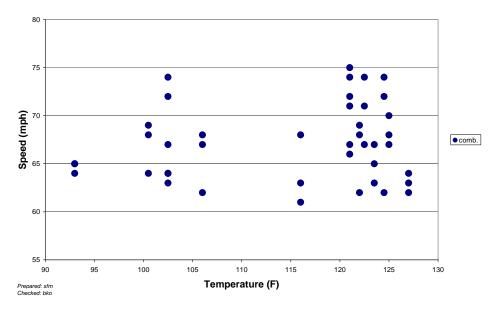


Figure 6-1 Pre-Validation Speed-Temperature Distribution – 350500 – 18-Aug-2008

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

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Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. The GVW is consistently underestimated at all speeds. There appears to be slightly less underestimation at medium speed. The scatter is similar for all speed groups.

10.0% 5.0% 5.0% 60 65 70 75 80 HLow Speed Medium speed High speed High speed

Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 350500 – 18-Aug-2008

Figure 6-3 shows the relationship between temperature and GVW percentage error. There is no apparent trend in error with increasing temperature. The slightly greater scatter at high temperature is more likely related to the number of observations than an actual temperature effect.

GVW Errors by Temperature

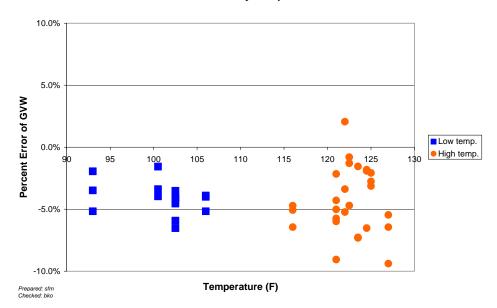


Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 350500 – 18-Aug-2008

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. There is no apparent influence of speed on spacing errors.

Drive Tandem Spacing vs. WIM Speed

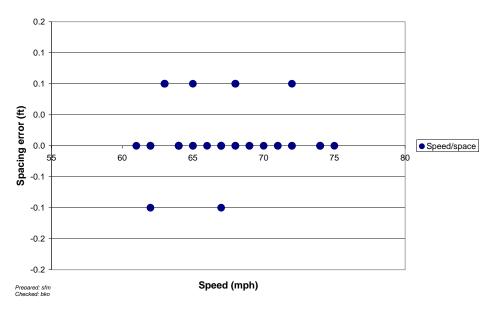


Figure 6-4 Pre-Validation Spacing vs. Speed - 350500 – 18-Aug-2008

6.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 93 to 110 degrees Fahrenheit for Low temperature and 111 to 127 degrees Fahrenheit for High temperature.

Table 6-2 Pre-Validation Results by Temperature Bin – 350500 – 18-Aug-2008

Element	95% Limit	Low Temperature 93 to 110 °F	High Temperature 111 to 127 °F
Steering axles	<u>+</u> 20 %	$-1.4 \pm 5.4\%$	$-2.6 \pm 4.2\%$
Tandem axles	<u>+</u> 15 %	$-4.6 \pm 5.1\%$	$-4.8 \pm 6.9\%$
GVW	<u>+</u> 10 %	$-4.1 \pm 2.8\%$	$-4.4 \pm 5.5\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: bko Checked:jrn

Table 6-2 shows the results by temperature bin. There is no major difference in the underestimation of loading statistics with temperature. The variability in GVW error at high temperature is about twice that of the low temperature group.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. There is no indication that temperature affects the individual trucks differently.

GVW Errors vs. Temperature by Truck

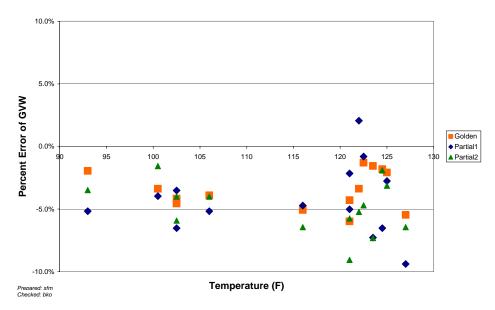


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 350500 – 18-Aug-2008

Figure 6-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-

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calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. There is a downward trend in error estimation for steering axles with increasing temperature.

Steering Axle Errors vs. Temperature

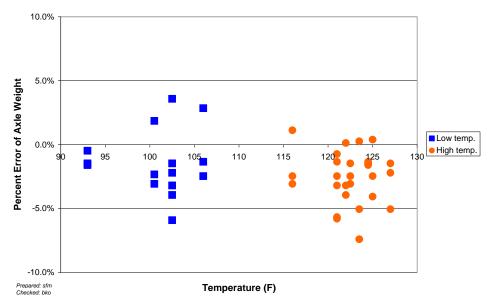


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 350500 -18-Aug-2008

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed – 61 to 65 mph, Medium speed – 66 to 70 mph and High speed -71 + mph.

Table 6-3 Pre-Validation Results by Speed Bin – 350500 – 18-Aug-2008

Element	95% Limit	Low Speed 61 to 65 mph	Medium Speed 66 to 70 mph	High Speed 71+ mph
Steering axles	<u>+</u> 20 %	$-2.5 \pm 5.4\%$	$-2.1 \pm 4.4\%$	$-1.7 \pm 5.2\%$
Tandem axles	<u>+</u> 15 %	$-5.8 \pm 5.6\%$	$-3.5 \pm 6.0\%$	$-4.9 \pm 7.1\%$
GVW	<u>+</u> 10 %	$-5.1 \pm 4.3\%$	$-3.2 \pm 4.4\%$	$-4.3 \pm 5.5\%$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$
			Prepared:	bko Checked:jrn

Table 6-3 shows that all loading statistics are underestimated for this truck population. The GVW estimates border on failure for low and high speed.

Figure 6-7 shows the GVW errors by truck. All of the trucks GVW are underestimated. The golden truck (squares) is limited to speeds below 68 mph due to an engine governor. The golden truck and the partial 2 truck (triangles) results do not appear to be influenced by speed. The partial 1 truck (diamonds) seems to have an upward trend in errors with speed.



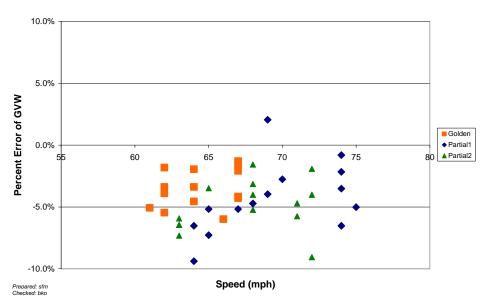


Figure 6-7 Pre-Validation GVW Percent Error vs. Speed Group - 350500 -18-Aug-2008

Figure 6-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. There is no apparent trend in steering axle error with speed.

Steering Axle Errors vs. Speed

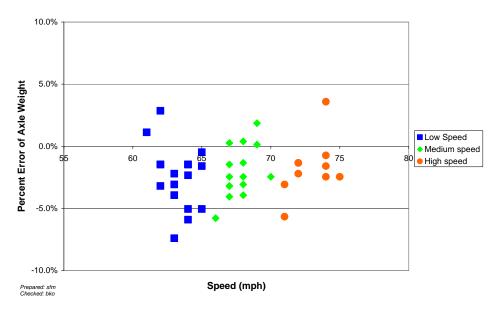


Figure 6-8 Pre-Validation Steering Axle Percent Error vs. Speed Group - 350500 – 18-Aug-2008

6.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to define unclassified vehicles. Classification 14 has been added to define unknown vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on the sample it was determined that there are zero percent unknown vehicles and zero percent unclassified vehicles. **This is not however consistent with data downloaded after the validation was complete.**

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is 3.9 percent. This exceeds the allowable rate for research quality data. It is however influenced by the fact that only four vehicles contributed to this result, one Class 8 and three Class 5 vehicles.

Table 6-4 Truck Misclassification Percentages for 350500 – 18-Aug-2008

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	0	5	33	6	0
7	N/A				
8	50	9	0	10	0
11	0	12	0	13	N/A

Prepared: bko Checked:jrn

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them a re matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero. The large values for Class 5 and Class 8 reflect three Class 5 vehicles and one Class 8 vehicle in this validation sample.

Table 6-5 Truck Classification Mean Differences for 350500 – 18-Aug-2008

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	0	5	- 33	6	0
7	N/A				
8	100	9	0	10	0
11	0	12	0	13	N/A

Prepared: bko Checked:jrn

These error rates are normalized to represent how many vehicles of the class are expected to be over or under counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

A limited investigation of the precision and bias of the speeds reported by the equipment was undertaken. The values were not within the expected tolerances. This may or may not be contributing to the misclassification observed.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: bko Checked:jrn

7 Data Availability and Quality

As of August 18, 2008 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site is shown in Table 7-1. The value for months is a measure of the seasonal variation in the data. The indicator of coverage indicates whether day of week variation has been accounted for on an annual basis. Previously collected data for this SPS experiment is omitted due to a lack of validation data.

Table 7-1 Amount of Traffic Data Available 350500 – 18-Aug-2008

Year	Classification Days	Months	Coverage	Weight Days	Months	Coverage
2008	65	4	Full Week	65	4	Full Week

Prepared: bko Checked:jrn

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Only Class 9 vehicles constitute more than 10 percent of the truck population. Based on the data collected following this validation the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the Regional Support Contractor on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-2 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-2 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.
- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-2 GVW Characteristics of Major sub-groups of Trucks – 350500 – 19-Aug-2008

Characteristic	Class 9
Percentage Overweights	0.1%
Percentage Underweights	0.0%
Unloaded Peak	40,000 lbs
Loaded Peak	80,000 lbs

The expected percentage of unclassified vehicles is 2.6 percent. This is based on the percentage of unknown and unclassified vehicles in the post-validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-3. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the post-validation period.

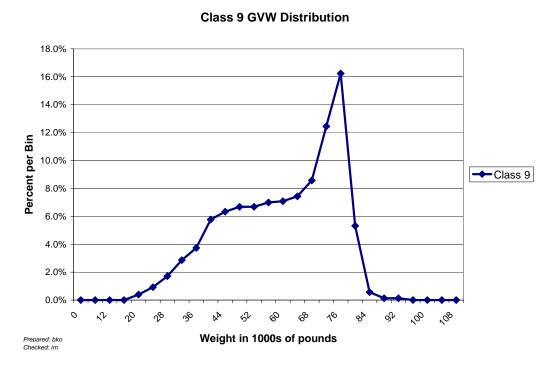


Figure 7-1 Expected GVW Distribution Class 9 – 350500 – 19-Aug-2008

Vehicle Distribution Trucks (4-15)

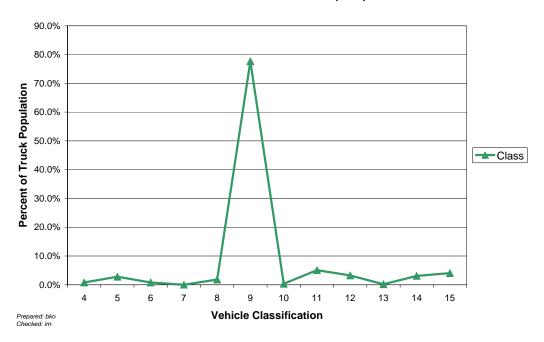


Figure 7-2 Expected Vehicle Distribution – 350500 – 19-Aug-2008

60.0% 50.0% Percentage of Trucks at Speed 40.0% 30.0% 20.0% 10.0% 0.0% 75 80 35 40 45 50 70 90 Speed (mph) Prepared: bko Checked: irn Speed Percentage

Speed Distribution For Trucks

Figure 7-3 Expected Speed Distribution – 350500 – 19-Aug-2008

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

Sheet 19 - Truck 1 - 3S2 loaded air suspension (3 pages)

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Sheet 19 - Truck 2 - 3S2 partially loaded air suspension (3 pages) Sheet 19 - Truck 3 - 3S2 lightly loaded air suspension (3 pages)

Sheet 20 – Classification verification – Pre-Validation (2 pages)

Sheet 20 – Classification verification – Post-Validation (2 pages)

Sheet 21 – Pre-Validation (3 pages)

Sheet 21 – Calibration Iteration 1 – (2 page)

Sheet 21 – Post-Validation (2 pages)

Calibration Iteration 1 Worksheets – (1 page)

Test Truck Photographs (9 pages)

LTPP Mod 3 Classification Scheme (1 page)

Final System Parameters (1 page)

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following this page. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the Pre-Validation and Post-Validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: New Mexico

SHRP ID: 0500

1.	General Information	1
2.	Contact Information	1
3.	Agenda	1
	Site Location/ Directions	
5.	Truck Route Information	3
	Sheet 17 – New Mexico (350500)	

Figures

Figure 4-1 - Site Location for 350500 in New Mexico	2
Figure 5-1 – Scale Location for 350500 in New Mexico	3
Figure 5-2 - Truck Route for 350500 in New Mexico	
Figure 6-1 - Site Map for 350500 in New Mexico	
Photos	
Dhata (1 250500 Hastmann 00 10 00 in a	0
Photo 6-1 - 350500_Upstream_08_18_08.jpg	
Photo 6-2 - 350500_Downstream_08_18_08.jpg	
Photo 6-3 - 350500_Solar_Panels_08_18_08.jpg	9
Photo 6-4 - 350500_Service_Mast_08_18_08.jpg	9
Photo 6-5 - 350500_Telephone_Service_Box_08_18_08.jpg	
Photo 6-6 - 350500_Modem_08_18_08.jpg	
Photo 6-7 - 350500_Cabinet_Exterior_08_18_08.jpg	
Photo 6-8 - 350500_Cabinet_Interior_Front_08_18_08.jpg	. 11
Photo 6-9 - 350500_Cabinet_Interior_Back_08_18_08.jpg	. 12
Photo 6-10 - 350500_Leading_Quartz_08_18_08.jpg	
Photo 6-11 - 350500_Trailing_Quartz_08_18_08.jpg	
Photo 6-12 - 350500_Leading_Loop_08_18_08.jpg	
Photo 6-13 - 350500_Trailing_Loop_08_18_08.jpg	

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Validation – NM 0500 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

1. General Information

SITE ID: 350500

LOCATION: Interstate 10 East at M.P. 50.2

VISIT DATE: August 18, 2008

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: Bruce Bender, 505-827-5508, bruced.bender@state.nm.us

Robert Meyers, 505-827-5466, robert.meyers@state.nm.us

Parveez Anwar, 505-827-5656, parveez.anwar@state.nm.us

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison: Steven Von Stein, 505-820-2028, steven.von.stein@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: No briefing requested for this visit

ON SITE PERIOD: August, 18 and 19, 2008, beginning at 9:00 a.m.

TRUCK ROUTE CHECK: See Truck Route

4. Site Location/ Directions

NEAREST AIRPORT: El Paso International Airport, El Paso, Texas

DIRECTIONS TO THE SITE: Approx. 2 miles west of Grant/Luna County Line.

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: Interstate 10 East at M.P. 50.2 (Latitude: 32.1932⁰ and

Longitude: -108.3015⁰)

WIM SITE LOCATION MAP: See Figure 4.1



Figure 4-1 - Site Location for 350500 in New Mexico

5. Truck Route Information

ROUTE RESTRICTIONS: None

SCALE LOCATION: Pilot Travel Center, Lordsburg, NM, I-10, exit 24, 505-542-3100,

Latitude: 32.34621, Longitude: -108.6935

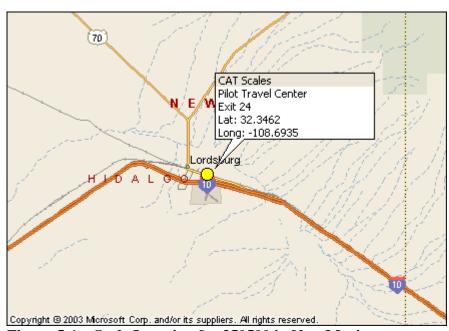


Figure 5-1 – Scale Location for 350500 in New Mexico

TRUCK ROUTE:

- Eastbound to Exit 55 Interchange (5.4 miles from site)
- Westbound to Exit 42 Interchange (8.4 miles from site)

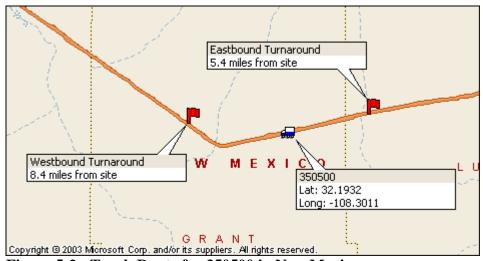


Figure 5-2 - Truck Route for 350500 in New Mexico

o. Sneet 17 –	New Mexico	0 (330300)			
1.* ROUTE _	<u>I-10</u>	_MILEPOST _	50.2	_LTPP DIRE	CTION - N S <u>E</u> W
Nearest	t SPS section	ΓΙΟΝ - Grade downstream of or to nearest ups	the site	350501_	
3.* LANE CO	NFIGURAT	ION			
	n LTPP direc			Lane width	_ <u>12_</u> ft
Median	$ \begin{array}{ccc} 1 - p \\ 2 - p \\ \underline{3} - g \\ 4 - n \end{array} $	hysical barrier rass		Shoulder -	1 – curb and gutter 2 – paved AC 3 – paved PCC 4 – unpaved 5 – none
Should	er width	_15.5 ft			3 – none
4.* PAVEMEN	NT TYPE _	asphalt			
Date <u>8/18/200</u>	<u>08</u> _ Photo Fi	E CONDITION lename <u>350500</u> llename <u>350500</u>	_Upstrea	am_08_18_08.	
		me			06.Jpg
6. * SENSOR 7. * REPLACI REPLACI	SEQUENCE EMENT ANI EMENT ANI	Loop – Quando D/OR GRINDIN D/OR GRINDIN D/OR GRINDIN	artz – Q NG <u> </u>	uartz – Loop _	/ /
KEI LACI	ZIVILZINI AINI	JOK GRINDII	··		′ — — — —
8. RAMPS OR Intersec distance	ction/drivewa	TIONS ay within 300 m	upstrea	m of sensor lo	cation Y / N
	ction/drivewa e	ay within 300 m	downst	ream of sensor	r location Y / <u>N</u>
		y used for turns	or passi	ng? Y / <u>N</u>	
9. DRAINAC	SE (Bending)	plate and load c	cell syste	ems only)	1 – Open to ground 2 – Pipe to culvert 3 – None
		te		overton V / N	
Ciearar	ice/access to	flush fines from	i unaer	system I / IN	

Validation – NM 0500 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites

10. * CABINET LOCATION				
Same side of road as LTPP lane \underline{Y} / N Median $\underline{Y} / \underline{N}$ Behind barrier $\underline{Y} / \underline{N}$				
Distance from edge of traveled lane _52 ft				
Distance from system <u>58</u> ft				
TYPE <u>336S</u>				
G. D. T. T. C.				
	CESS controlled by LTPP / STATE / JOINT?			
Contact	t - name and phone number <u>Robert Meyers (505) 827-5466</u>			
Alterna	te - name and phone number			
11. * POWER				
Distance to cal	oinet from drop 12 ft Overhead / underground / solar /			
AC in cabinet?	<u> </u>			
Service provide	erN/A Phone number			
12. * TELEPHONE				
	oinet from drop 137 ft Overhead / under ground / cell?			
Service provide	er Phone Number _(575) 546-9131_			
10 * GNGTEN (C	o 'apro			
	are & version no.)iSINC			
Computer conf	nection – RS232 / Parallel port / USB / Other			
14. * TEST TRUCK T	TURNAROUND time27 minutes DISTANCE _30 miles			
15. PHOTOS	FILENAME			
Power source	350500_Solar_Panels_08_18_08.jpg			
	350500_Service_Mast_08_18_08.jpg			
Phone source	350500_Telephone_Service_Box_08_18_08.jpg			
	350500_Modem_08_18_08.jpg			
Cabinet exterior	350500_Cabinet_Exterior_08_18_08.jpg			
Cabinet interior	350500_Cabinet_Interior_Front_08_18_08.jpg			
	350500_Cabinet_Interior_Back_08_18_08.jpg			
Weight sensors	350500_Leading_Quartz_08_18_08.jpg			
	350500_Trailing_Quartz_08_18_08.jpg			
Classification sensors	250500 7 11 7 00 10 00 1			
Other sensors	350500_Leading_Loop_08_18_08.jpg			
Description I am	350500_Trailing_Loop_08_18_08.jpg			
Description Loop				
	at sensors on LTPP lane			
350500 Downstream 08 18 08.jpg Upstream direction at sensors on LTPP lane				
350500 Upstream 08_18_08.jpg				
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Validation – NM 0500 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites MACTEC Ref. 6420070022 2.106 9/8/2008 Page 6 of 14

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	,,,	/ 1	V	

GPS Coordinates: Latitude: 32.1932° and Longitude: -108.3015°
Closest Amenities in Deming, NM - Various Hotels, Restaurants, Gas Stations
Etc., (31 miles) Exits 81, 82A & B, 85
Speed Limit – 75 mph
Communications Software – ProComm Plus
COMPLETED BYDean J. Wolf
PHONE 301-210-5105 DATE COMPLETED 8/18/2008

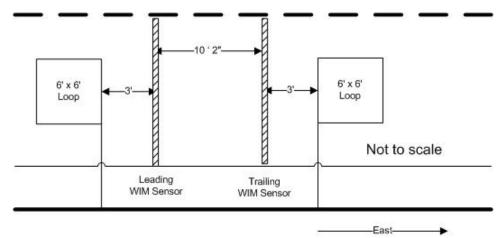


Figure 6-1 Sketch of Equipment Layout - 350500 - 18-Aug-2008

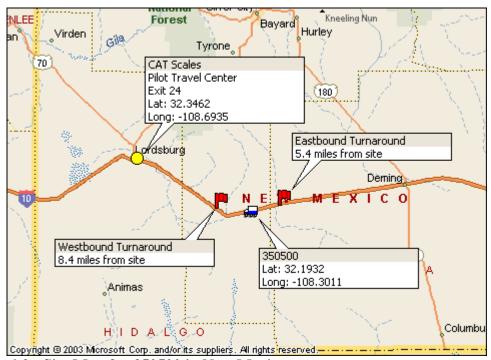


Figure 6-2 - Site Map for 350500 in New Mexico



Photo 6-1 - 350500_Upstream_08_18_08.jpg



Photo 6-2 - 350500_Downstream_08_18_08.jpg



Photo 6-3 - 350500_Solar_Panels_08_18_08.jpg



Photo 6-4 - 350500_Service_Mast_08_18_08.jpg



Photo 6-5 - 350500_Telephone_Service_Box_08_18_08.jpg



Photo 6-6 - 350500_Modem_08_18_08.jpg



Photo 6-7 - 350500_Cabinet_Exterior_08_18_08.jpg



Photo 6-8 - 350500_Cabinet_Interior_Front_08_18_08.jpg



Photo 6-9 - 350500_Cabinet_Interior_Back_08_18_08.jpg



Photo 6-10 - 350500_Leading_Quartz_08_18_08.jpg



Photo 6-11 - 350500_Trailing_Quartz_08_18_08.jpg



Photo 6-12 - 350500_Leading_Loop_08_18_08.jpg

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Photo 6-13 - 350500_Trailing_Loop_08_18_08.jpg

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[0100]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/200</u>	<u>8</u>

1.	DA	ATA PROCESSING –
	a.	Down load – State only LTPP read only LTPP download LTPP download and copy to state
	b.	Data Review – State per LTPP guidelines State – Weekly Twice a Month Monthly Quarterly LTPP
	c.	Data submission – State – Weekly Twice a month Monthly Quarterly LTPP
2.	ΕÇ	QUIPMENT –
		Purchase – State LTPP
	b.	Installation − ☐ Included with purchase ☐ Separate contract by State ☐ State personnel ☐ LTPP contract
	c.	Maintenance – Contract with purchase – Expiration Date _5 years from installation_ Separate contract LTPP – Expiration Date Separate contract State – Expiration Date State personnel
	d.	Calibration – Vendor State LTPP
	e.	Manuals and software control − ☐ State ☐ LTPP
	f.	Power – i. Type – Overhead Underground Solar ii. Payment – State LTPP N/A

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/2008</u>	3

	g.	Communication –
		i. Type − ii. Payment −
3.	PA	AVEMENT –
	a.	Type − ☐ Portland Concrete Cement ☐ Asphalt Concrete
	b.	Allowable rehabilitation activities – Always new Replacement as needed Grinding and maintenance as needed Maintenance only No remediation
	c.	Profiling Site Markings – Permanent Temporary
4.	ON a.	N SITE ACTIVITIES – WIM Validation Check - advance notice required <u>2</u> ☐ days ☐ weeks
	b.	Notice for straightedge and grinding check2
		ii. Accept grinding − ☐ State ☐ LTPP
	c.	Authorization to calibrate site – State only LTPP
	d.	Calibration Routine – LTPP – Semi-annually Annually State per LTPP protocol – Semi-annually Annually State other –

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/2008</u>	3

	e.		Vehicles			
		i.	Trucks – 1st – <u>Air suspension 3S2</u> 2nd – <u>3S2 different weig</u> 3rd – <u>4th</u> – <u> 4th</u> – <u> </u>	☐ State ht/suspension ☐ State ☐ State		⊠ LTPP
		ii.	Loads –	State	LTPP	
		iii.	Drivers –	State	LTPP	
	f.	Contr	ractor(s) with prior successful ex	perience in WIM	I calibration ir	state:
	g.	Acces i.	ss to cabinet Personnel Access – State only Solution LTPP			
		ii.	Physical Access – Key Combination			
	h.	State	personnel required on site -	☐Yes ⊠No)	
	i.	Traffi	ic Control Required –	☐Yes ⊠No)	
	j.	Enfor	cement Coordination Required -	- ∐Yes ⊠No)	
5.	SI'a.		ECIFIC CONDITIONS – s and accountability –			
	b.	Repor	rts –			
	c.	Other	:			
	d.	Speci	al Conditions –			
6.	CC	ONTAC	CTS –			
	a.	Equip	oment (operational status, access,	, etc.) –		
			Name: Roy Czinku	Pho	ne: <u>(306) 653-6</u>	<u>6627</u>
			Agency: IRD			

SHEET 18	STATE CODE	[35]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[<u>0100</u>]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy) <u>8/20/2008</u>	

	b.	Maintenance (equipment) –	
		Name: Roy Czinku	Phone: (306) 653-6627
		Agency: <u>IRD</u>	
	c.	Data Processing and Pre-Visit Data –	
		Name: Roy Czinku	Phone: (306) 653-6627
		Agency: <u>IRD</u>	
	d.	Construction schedule and verification -	-
		Name:	Phone:
		Agency:	
	e.	Test Vehicles (trucks, loads, drivers) –	
		Name:	Phone:
		Agency:	480-641-3500
	f.	Traffic Control –	
		Name:	Phone:
		Agency:	
	g.	Enforcement Coordination –	
		Name:	Phone:
		Agency:	
h.	Neare	est Static Scale	
		Name: Pilot Travel Center	Location: Lordsburg NM Exit 24
		Phone: 505-542-3100	

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[35]
*SHRP SECTION ID	[0500]

SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR)	[8/18/2008]
2.	* TYPE OF EQUIPMENT CALIBRATED WI	MCLASSIFIER <u>X</u> BOTH
	* REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X_ OTHER (SPECIFY) LTPP Validation	RESEARCHTRAININGNEW EQUIPMENT INSTALLATION
4.	* SENSORS INSTALLED IN LTPP LANE AT THIS SIT BARE ROUND PIEZO CERAMIC BACCHANNELIZED ROUND PIEZO LOCHANNELIZED FLAT PIEZO X IN OTHER (SPECIFY)	TE (CHECK ALL THAT APPLY): RE FLAT PIEZO BENDING PLATES AD CELLS _X_ QUARTZ PIEZO DUCTANCE LOOPS CAPACITANCE PADS
5.	EQUIPMENT MANUFACTURERIRD/ PAT Traffic	2
	WIM SYSTEM CAL	IBRATION SPECIFICS**
6.**	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE	(Y/N) X TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	3 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	14 PASSES PER TRUCK TRUCK TYPE SUSPENSION 1
7.	SUMMARY CALIBRATION RESULTS (EXPRESS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW DYNAMIC AND STATIC SINGLE AXLES DYNAMIC AND STATIC DOUBLE AXLES	,
8.	3 NUMBER OF SPEEDS AT WHICH CALIBE	RATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	<u>65 70 75</u>
10. 11.*	* IS AUTO-CALIBRATION USED AT THIS SITE? (IF YES, LIST AND DEFINE AUTO-CALIBRATION USED AT THIS SITE? (Output Description:	Y/N) <u>N</u>
	CI ASSIFIER T	EST SPECIFICS***
12.*		DLUME MEASUREMENT BY VEHICLE CLASS:
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIMEX_ NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 <u>100</u>	ES CLASSIFICATION: FHWA CLASS FHWA CLASS FHWA CLASS FHWA CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES:	
	RSON LEADING CALIBRATION EFFORT: <u>Dean J. V</u> DNTACT INFORMATION: <u>301-210-5105</u>	Wolf, MACTEC rev. November 9, 1999

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[]
*STATE CODE	[35]
*SHRP SECTION ID	[0500]

SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR)	[8/19/2008]
2.	* TYPE OF EQUIPMENT CALIBRATED	WIMCLASSIFIER _X_BOTH
	* REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION X OTHER (SPECIFY) LTPP Validation	RESEARCHTRAININGNEW EQUIPMENT INSTALLATION
	* SENSORS INSTALLED IN LTPP LANE AT THISBARE ROUND PIEZO CERAMICCHANNELIZED ROUND PIEZOCHANNELIZED FLAT PIEZO XOTHER (SPECIFY)	SITE (CHECK ALL THAT APPLY): BARE FLAT PIEZO BENDING PLATES LOAD CELLS _X_ QUARTZ PIEZO INDUCTANCE LOOPS CAPACITANCE PADS
5.	EQUIPMENT MANUFACTURERIRD/ PAT Tra	nffic
	WIM SYSTEM C	ALIBRATION SPECIFICS**
6.**	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCA	ALE (Y/N) X TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	3 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	14 PASSES PER TRUCK TRUCK TYPE SUSPENSION 1
7.	SUMMARY CALIBRATION RESULTS (EXPRIMEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW DYNAMIC AND STATIC SINGLE AXLES DYNAMIC AND STATIC DOUBLE AXLES	,
8.	3 NUMBER OF SPEEDS AT WHICH CAL	IBRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH) _	657075
10. 11.*	CALIBRATION FACTOR (AT EXPECTED FRE * IS AUTO-CALIBRATION USED AT THIS SITE IF YES, LIST AND DEFINE AUTO-CA	E? (Y/N) <u>N</u>
	<u>CLASSIFIE</u>	R TEST SPECIFICS***
12.*	** METHOD FOR COLLECTING INDEPENDENT VIDEOX_ MANUAL	VOLUME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COU	NT TIME _X NUMBER OF TRUCKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHION *** FHWA CLASS 9 0 *** FHWA CLASS 8 50	FHWA CLASS FHW
	*** PERCENT "UNCLASSIFIED" VEHICLES:	FHWA CLASS
	RSON LEADING CALIBRATION EFFORT: <u>Dean</u> DNTACT INFORMATION: <u>301-210-5105</u>	J. Wolf, MACTEC rev. November 9, 1999



LTPP Traffic Data		* SPS PROJEÇT ID	0 5 0 0
*CALIBRATION TEST TRUCK # Rev. 08/31/01	1	* DATE 3/18/5°	8 1/10/08
Kev. 06/31/01			Parise In Alan
PART I.			PRIVEN-ALBER 486-694-6
1.* FHWA Class 2.* Numb	er of Axles _	, big	per of weight days 2
AXLES - units (lbs)/100s lbs / kg			muck
GEOMETRY			TNORE 620 TNOREN 846
8 a) * Tractor Cab Style - Cab Over Engine /	Conventional	b) * Sleeper Cal	o? (Y) (N)
9. a) * Make: INTERMENT b) * Model:	9400 i		
10.* Trailer Load Distribution Description:			
PALLETIZED SUPER	SAMOS OF	TIRE BUFF	ines .
LAPPED EVENLY AL			
C. M			
 11. a) Tractor Tare Weight (units): b). Trailer Tare Weight (units): 12.* Axle Spacing – units m / feet and ir 		***	
<u></u>		**************************************	
A to B 17.4 B to C 4	<i>₩</i> , <i>₩</i> , (C to D 33.2	
D to E	·	E to F	MARINETY MAIN
Wheelbase (measured A to last)		omputed <u>59.1</u>	***************************************
13. *Kingpin Offset From Axle B (units)	$\frac{+1.8}{\text{(+ is to the }}$	rear)	an.
SUSPENSION			
Axle 14. Tire Size 15.* Suspension	n Description (le	af, air, no. of leaves.	, taper or flat leaf, etc.)
	ull Sent		•
B 7512 225 A15	-		
C 75R 22.5 A	· Ugava,		
D 752 22.5 A	4 weening		
E 7512225 A1	***		
F	ν ^{*0} ι.,		
¥.			

* STATE_CODE

3 5

Sheet 19

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		Sheet 19			TATE_CODE	3_5_					
		TPP Traffic Data		······································	PS PROJECT II)	0 5 0 (B/18/0°				
Rev. 08/31/0	*CALIBRATION TEST TRUCK # 1 * DATE										
Rev. 08/31/0	i										
PART II				Day 1							
	*b) Average Pre-Test Loaded weight *c) Post Test Loaded Weight *d) Difference Post Test – Pre-test -630										
Table 5. Ra	iw data – Axl	e scales – pre-	test								
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW				
1	11700	165%0	18280	16130	14(30		77120				
2	11700	1520	16570	16(30	16130		77100				
3											
Average	11700	16575	16575	16130	16130		771%0				
Table 6. Ra	nw data – Axlo	e scales –									
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW				
1											

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11440	16430	16430	16100	16100		76500
2	11440	16420	16420	16090	16090		76460
3							
Average	11440	16425	(645	14095	(6095		76480

Measured By A W	Verified By	<u> </u>	Weight date	8)18/29
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Sheet 19	* STATE_CODE	3 5
LTPP Traffic Data	* SPS PROJECT ID	0 5 0 0
*CALIBRATION TEST TRUCK #_1	* DATE	With

Day 2

7.2

*b) Average Pre-Test Loaded weight

be

*c) Post Test Loaded Weight

*d) Difference Post Test – Pre-test

74010

Table 5.2. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11440	16430	16430	16130	10130		76560
2	tivyo	(6430	16430	(6130	16130		76560
3							
Average	11440	16430	16430	14130	16130		7680

Table 6.2. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1.1							
2					·		
3							
Average							

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11581	14220	16220	16140	16140		76006
2	1200	16290	16290	llerzo	Merzo		76020
3					;		
Average	11740	16255	1 1 255	16130	16130		76010

Measured By d	Verified By	\M	Weight date & LA YE
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Sheet 19	* STATE_C	* STATE_CODE				
LTPP Traffic Data	* SPS PROJ		0500			
*CALIBRATION TEST TRUCK # 2 Rev. 08/31/01	* DATE	8/18/08	8/14/00			
PART I.		71/-	JENNY -412-86			
1.* FHWA Class <u>9</u> 2.* Number of	f Axles _5	Number of weight				
AXLES - units -(lbs) 100s lbs / kg		TAMILEN 5				
GEOMETRY		1 VP (CEN)	03			
8 a) * Tractor Cab Style - Cab Over Engine / Cor 9. a) * Make: (GTE/G) b) * Model:	The transfer of the second	eper Cab? Y/N				
10.* Trailer Load Distribution Description:						
PALLETIZED SYPEN SACKS	TO THE BUT	ナルと				
LOACED EVENLY ALONS	TAKILER					
b). Trailer Tare Weight (units): 12.* Axle Spacing – units m / feet and inches A to B B to C D to E	s / feet and tenths C to D	32-0				
***************************************		<i>√</i> 8 \$				
Wheelbase (measured A to last)		····				
SUSPENSION						
A 75R 24.5 2 FUL B 75R 24.5 AIR C 25R 24.5 AIR D 11R 22.5 AIR	scription (leaf, air, no. o く Sfrルルン (e	543¢				
E 11222,5 AIR						
F						

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Sheet 19	* STATE_CODE	3 5
LTPP Traffic Data	* SPS PROJECT ID	0 5 0 0
*CALIBRATION TEST TRUCK #_2_	* DATE	\$11210

PART II

Day 1

*b) Average Pre-Test Loaded	weight
*c) Post Test I goded Weight	

*d) Difference Post Test – Pre-test

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	いっこの	15620	15620	00911	11900		60160
2	11120	157, 30	15630	11900	11200		66780
3							
Average	11720	15625	157,25	11900	11900		しょうつの

Table 6. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
. <u>i</u>							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11440	Istoryto	15640	11690	11690		4,100
2	11460	15430	157030	11690	11690		66100
3							
Average	11450	15635	15635	11690	11690		66100

Measured By	Ku	Verified By	mle	Weight date	68/31/8
	*		V		Į į

Sheet 19	* STATE_CODE	3 5
LTPP Traffic Data	* SPS PROJECT ID	0500
*CALIBRATION TEST TRUCK # 2	* DATE	

Day 2

7.2

*b) Average Pre-Test Loaded weight

*c) Post Test Loaded Weight

*d) Difference Post Test – Pre-test

67130

106410

-720

Table 5.2. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11900	15880	15880	१८७५०	11740		67140
2	11920	15880	15880	11720	11720		67120
3							
Average	11910	158330	12,880	11730	4730		67130

Table 6.2. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
<u>1</u>							
_ 2							
3							
Average							

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11600	15730	15730	11650	11650		66360
2	11580	15750	15750	11690	11690		66460
3							
Average	11590	15740	15740	11170	11670		66410

Measured By A	Verified By	Weight date_	<u> 3)(9/08</u>
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	Sheet 19	* STATE_CODE	3_5_
	TPP Traffic Data	* SPS PROJECT ID	0500
Rev. 08/31/01	TION TEST TRUCK #_3	*DATE 8/18/08	
PART I.			DANA 701-2-19-99
l.* FHWA Class <u></u>	2.* Number of Ax	les 5 Number of we	eight days
AXLES - units - (bs)	100s lbs /kg	77	ruck 622
GEOMETRY		7	MILEN 837
			N
9. a) * Make INTENT	PY's Novel: 9900	ĭ×	
10.* Trailer Load Distrib	A	1485	
6 MTO LISED	SUPEN SAKK & EF	TIME BUFFERS	
COMDED EV	enly Along-Tra	MER	
			NAMA AND AND AND AND AND AND AND AND AND AN
b). Trailer Tare Weig	ht (units):ht (units):		
12.* Axie Spacing – unit	s m / feet and inches / f	teet and tenths	
A to B 19.6	B to C	C to D 32.7	
	D to E	E to F	
Wheelbase (meas	ured A to last)	Computed60. T	
13. *Kingpin Offset Fron	n Axle B (units)	3 ()_	
	(+;	is to the rear)	
SUSPENSION			
Axle 14. Tire Size	15.* Suspension Descrir	otion (leaf, air, no. of leaves, taper or	r flat leaf etc \
A () 12 22 S			,
B // t2 22.3			
C // 12 22.5			
D 752-22-5			
E 7.572-22-,S			
F			
λ			

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Sheet 19	* STATE_CODE	3 5
LTPP Traffic Data	* SPS PROJECT ID	0 5 0 0
*CALIBRATION TEST TRUCK #_3_	* DATE	80/3/15

PART II

Day 1

*b) Average Pre-Test Loaded weight

57690

*c) Post Test Loaded Weight

57110

*d) Difference Post Test – Pre-test

<u>-580</u>

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11680	11690	11690	11320	11320		57700
2	KGGO	11700	11700	1(310	(1310		576%0
3							
Average	11670	11695	11695	11315	11315		57 L90

Table 6. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
2				·			
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11380	11550	11550	11300	11300		57080
2	11500	11490	11490	11330	11330		57140
3							
Average	11440	11520	11520	11315	11315		57110

Measured By	Verified By	~ 2\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	Weight date	8/18/08
V			•	

		Sheet 19		* S	* STATE_CODE		
		PP Traffic Data			* SPS PROJECT ID		
tev. 08/31/0		ION TEST TRU	JCK #_3	* D	ATE		
.ev. 06/31/C	<i>,</i> 1						
				Day 2			
.2		Pre-Test Loa		<u>56190</u>			
	•	t Loaded Wei	~~	<u> 57640</u>			
	*a) Differen	ce Post Test -	- Pre-test	<u> - 553</u>	<u> </u>		
able 5.2.	Raw data – Ax	le scales – pro	e-test				
ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
	11920	11800	17800	11330	11330		58180
	11920	11010	11810	11330	11330		582o a
verage	11920	11805	11805	11330	11330		58190
able 6.2.	Raw data – Ax	le scales –		1			
able 6.2.	Raw data – Ax Axle A	le scales – Axle B	Axle C	Axle D	Axle E	Axle F	GVW
ass			Axle C	Axle D	Axle E	Axle F	GVW
ass			Axle C	Axle D	Axle E	Axle F	GVW
ass			Axle C	Axle D	Axle E	Axle F	GVW
ass			Axle C	Axle D	Axle E	Axle F	GVW
			Axle C	Axle D	Axle E	Axle F	GVW
ass		Axle B		Axle D	Axle E	Axle F	GVW
verage	Axle A	Axle B		Axle D	Axle E	Axle F	GVW
verage	Axle A Raw data – Axl	Axle B e scales – pos	t-test				
ass	Axle A Raw data – Axl Axle A	e scales – pos	t-test Axle C	Axle D	Axle E		GVW 57620
verage able 7.2 I	Axle A Raw data – Axl Axle A	e scales – pos	Axle C	Axle D	Axle E		GVW

Weight date 8/19/08

Measured By Verified By _____

Sheet 20	* STATE_CODE	3 5
LTPP Traffic Data	*SPS PROJECT_ID	0 5 0 0
Speed and Classification Checks * 1 of* 2	* DATE	8/18/08
Rev. 08/31/2001		

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
7)9	9	8879	つサ	9	73	9	8985	74	9
75	9	8880	74	2	64	1	8998	64	11
62	9	8888	63	9	66	9	9061	65	9
つり	9	8889	7)1	9	66	9	9-62	66	9
75	9	8897	74	9	69	9	9004	68	9
73	9	8898	73	9	56	8	2009	56	5
62	9	8900	62	9	73	9	9015	74	9
59	2	8953	(4	9	77	/)	9019	72-	11
72	ह	8906	72	Š	68	9	9020	67	9
63	9	8909	62	9	66	11	9030	66	11
57	9	8915	56	9	6=	5	9035	60	5
73	5	8916	73	5	66	9	9037	la la	9
64	9	891フ	64	9	63	9	ナナーと	63	9
73	<u></u>	もりる	73	5	63	9	9046	63	9
66	9	8923	65	9	G5	9	9047	65	9
67	2	8925	67	9	73	9	9048	72	9
フロ	9	8927	6 070	9	68	9	9054	68	9
65	5	8 <i>95</i> 7	66	5	64	9	9055	60	9
68	9	&95€	67	9	75	9	9062	69	9
65	8	8959	66	8	67	9	9064	67	9
73	9	8261	73	9	S)	9	9071	60	9
6)	9	ての65	68	9	74	9	9574	24	9
フミ	9	8975		9	73	9	9075	72	9
68	9	8 <i>9</i> 7 ?	47	9	75	10	ダロフフ	74	/5
66	9	1368	66	9	62	9	クーフラ	61	

Recorded by MARIA Direction E Lane J Time from // 500 to 12:02 PM 6420070022 SPSWIM TO 25 35 2.106 0500 Pre-Validation Sheet 20.doc

Sheet 20	* STATE_CODE	3 5
LTPP Traffic Data	*SPS PROJECT_ID	0 5 0 0
Speed and Classification Checks * 2 of* >	* DATE	8/18/08

	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
	73	9	8646	19	9	40	9	8752	(r)	Class O)
	72	9	8648	7)2	9	68	2	8787	68	9
	71	9	8659	~~))	9	73	9	<i>を</i> フ <i>を</i> ጛ	67)	9
	63	9	8660	63	9	75	9	8792	75	9
	77	9	8663	つつ	9	77)	9	8800	777	9
	64	2	8664	63	9	63	9	8803	63	9
	62	9	8682	42	9	75	6	8857	つり	6
K	57	8	8687	ラフ	5	61	9	8808	60	9
	#66	11	8695	66	11	67	9	8812	69	9
	69	9	8696	40070	9	フン	9	8 <i>81</i> 3	73	9
	62	9	8697	62	9	68	9	8816	67	9
	75	9	8698	7 5	9	72_	9	8 (38	71	9
	68	9	4699	つり	9	72	9	8819	フル	9
	62	4,9	8703	62	9	73	9	8820	フロ	9
	73	12-	8704	つる	9012	64	9	8821	65	<u>.</u> 9
	68	9	8715	68	9		<i>99</i>	8822	64	9
	68	4	8719	69	64	75	12	8824	フト	12
	78	6	をフょフ	8)	(22	24	9	8926	フ3	9
	68	9	8730	69	9	70	9	833)	つノ	9
	71		8731	72	9	65	2	8835	64	9
		2	8741	72-	<i>5</i> 9	65	9	8837	66	9
	24	9	8744	73	2	58	9	8861	59	9
	73	g	8745	73	9	72	Ž.	8864	7/	9
	64	9	8747	64	Ğ	۵۲	2	8843	70	9
	74	6	8750	フィ	6	74	9	8876	75	9

Sheet 20	* STATE_CODE	3 5
LTPP Traffic Data	*SPS PROJECT_ID	0 5 0 0
Speed and Classification Checks * / of* 2	* DATE 2 /	19/08

	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
	73	9	47/	76	9	76	9	522	7.5	ġ
	7]	9	474	7.1	9	70	9	523	75	9
	60	9	479	<i>5</i> y	9	64	9	524	64	9
	68	9	481	フロ	2	68	9	525	70	9
	74	9	483	73	9	65	9	528	69	9
	72	9	484	フ/	2	72	9	529	73	9
	<u> </u>	8	485	71	B	63	9	531	64	9
	66	//	486	66	1]	72	5	532	フチ	5
	71	9	487	フ	9	69	9	534	フロ	9
	65	9	489	65	9	6°	9	536	6]	9
	68	9	490	69	9	67	12	537	68	12
	75	9	494	72	9	68	9	54)	69	9
	70	9	499	つも	9	62	9	543	63	9
	73.	9	54	7/	9	62	9	544	6	9
	75	9	503	68 76	\$ 9	68	9	545	66	9
*	62	8	556	62	5	68	9	581	68	ġ
	72	9	509	つる	9	65	9	591	65	9
	71	9	510	フロ	9	64	9	592	64	.57'
	75	9	511	73	9	67	9	.5 94	67	9
	60	9	512	60	2	73	9	596	24	9
	74	9	513	74	9	67	<u> </u>	597	66	9/1
	67	9	514	69	9	58	2	5 9 8	58	9
	68	9	516	69	9	70		600	7/	<i>.</i> "
	72	8	518	73	88	46	5	601	67	9
	<i>6</i>	9	519	68	9	62	9	604	71	9

Recorded by MARK 2 Direction E Lane Time from 11:15 to 11:48 Am
6420070022 SPSWIM_TO_25_35_2.106_0500_Post-Validation_Sheet_20.doc

Sheet 20	* STATE_CODE	3 5
LTPP Traffic Data	*SPS PROJECT ID	0 5 0 0
Speed and Classification Checks * 2 of* 2	* DATE \$ / 19	108

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
63	9	606	63	9	つけ	9	638	74	9
64	9	40フ	64	9	75	9	640	78	9
55	9	609	59	9	67	9	642	67	9
69	9	616	6)	9	67	2	644	66	9
66		60	67	11	66	9	645	66	9
67	9	613	68	9	68	9	646	68	9
75	9	614	76	9	64	9	653	65	9
67	9	415	67	9	73	9	656	72	9
. 68	9	616	69	9	73	9	657	73	2
69°	9	617	70	. 9	72	9	659	72 ₆₈	9
- 63	9	618	65	9	63	3	661	66	9
<i>65</i>	12	620	65	12	45	9	662	65	9
G5	9	62-1	67	9	72.	9	663	73	9
75	9	622	The	9	フン	9	688	70	9
70	9	623	70	9	71	9	691	71	9
62	9	624	65	9	62	9	693	62.	9
63	9	625	64	9	72	9	694	70	9
68	9	627	69	9	73	9	695	フチ	9
66	71	623	65	@]]	47	9	696	69	9
65	9	62 9	66	9	73	9	637	73	9
62	9	631	62	9	69	9	698	68	9
フも	9	638	70	g	<i>1</i> 3	9	699	73	9
つ	9	634	69	9	64)/	7780	64	/
64	9	635	63	9	フを	<u> </u>	762	78	A I
69	9	637	69	Ğ	44	9	704	66	9

Recorded by MARK Z Direction E Lane / Time from //:48 to 12:12 PM 6420070022 SPSWIM_TO_25_35_2.106_0500_Post-Validation_Sheet_20.doc

Sheet 21	* STATE_CODE	3.5
affic Data	*SPS PROJECT_ID	0 5 0 0
ystem Test Truck Records of 3	* DATE	8/18/08

E-F space																
D-E space		E		3	P. 3-	3	- Annual	62	9	3	0 +	Q.		9	<i>3</i> -	- Ju
c-D	ci	37,0	27.6	8	8 8	32.3	33.2	37.6	かな	(d)	32.6	およ	7.8	376	78	33.2
B-C space	- E	50	ナ	5	5	. politicae.	ナ	4.3	ナチ	ナ ナ	ry T	3	J	(Y)	3	3
A-B space	3.	<u>'0</u>	5	ナンガシ	8.618.69	0	ナム	0.0	5.5	Ċ.	2.5	2 N	C.	CE	25.5	2.5
@W.	5.3	<i>w</i> 0	か ど	7 5.7	6.60	N 3	3	<u></u>	Jo Lo	9.80	ä	0 1 1 1	89.50	63.0	K	72.5
Axle F weight																
Axle E weight.		76	54245	19 CK	The state of the s	200	是	17/3g	26	1897	90	52/53	2000	61/65	克克	200
Axle D weight.	84/66	19/1	30	8C/2C	39	30	数元	75/95	26/24	22	DE CE	52	21/55	SE SE	25	2
Axle C weight.	63,58	24/76	12/2	2	7	595)	4/2	177C	73/20	78/28	THE STATE OF THE S	THE	% /%	T. B. C.	53/56	67
Axle B weight.	80/37	THE	38	\$ C. S.	18/2	566	18/35		536	76/30	Wec.	25/25	78/22	2/2	52/20	38/28
Axle A weight.	75/25	64/50	75/5	55/25	300	57/55	59/52	5/28	23/129	h5/85	35.4	58/53	S. S	396	75/25	15/49
Speed	42	5	69	かつ	3	8	さ	t	7	69	少	T)	19	()	89	()
Record No.	SCCY	8665	7778	CACE	250	8756	(OHO)	(28.2)	8839	ENS	8225	8937	18	933	soyo	100
Time	9:40	67:3	61.16	7:2	<u>C</u>		\$ <u>0</u>	16:44 882.	3	0:12		6	(6:1)		7	1965:21
Pass		H5-mmaqran)	, general trans	H	7	4	\mathcal{C}	a	4		Jenn.	Jun	rv.	Ŋ	LŊ	9
720 <u>%</u>	Makestonatents	ત્ત્રી	M	Constablished	C	U	1.449° (2.44° (2.44°)	d	(1)	Standard or special standa	d	(~	White was	(d)	(n)	watership
Radar Speed	63	t o	S.	64	89	89	63	and me	(m)	0	E	49	9	89	69	23
Pvmt	8	87	8	100,5	n (g)	S.CO	ひてり	22	2	7	(C) A	72,27	90	<u>9</u> 0	30	2

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Sheet 21	* STATE CODE	3.5
LTPP Traffic Data	*SPS PROJECT ID	0 5 0 0
WIM System Test Truck Records 🔔 of B	* DATE	40/81/8

			·	т	.,			·,	·	·						
E-F space																
D-E space	9-	o,	and the same	0 5	3	- Level	0,	3-		9.5		مسير	3	3	Ĵ	0
c-D sbace	32.7	32.3	in Signature of the Sig	32.7	32.3	(v)	37.8	63	320	32.0	33	33.2	32.8	32.3	33.	32.7
B-C space	50	2	3	t,	<i>J</i>		4	3	J***	[A]	ナデ	35		チェ	1 5	5.7
A-B space	6.6	5.0 0.0	7.3	6.3	2.6	C.	0	7.0	オベ	6,	<u>0</u> 7	OF THE PROPERTY OF THE PROPERT	200	6	2.	67
	0.50	ri R	2	62.6	8 0	(A)	020	でま	27	7.00	S	75.2	2.50	75		25
Axle F weight					- 4 3	*								**		
Axle E weight.	22		20/26	29/03	N.	78	500	200	200	3/3	N. A.	35/20	60	25	No.	Ch
Axle D weight.	S. S	200	200	3362	N OI	200	25	N SS	25/23	S. S	16 July 18 Jul	160	# XX	The second	48/60	2673
Axle C weight.	300	25	The state of the s	44/	15/2×	8%8	22	77.	2990		2/2	78/08	2000	52,52	346	722
Axle B weight.	26/26	283	26/33	34/20	17/84	78/2	200	200	75/83		48,750		7		28/2	3
Axie A weight.	200	75/85	63/85	2/12	3%	75/85	25/25	75/25	25/85	123/4	52/22	56/55	200	2000	75/85	572
Speed	74	- 2C		29	(1)		1		7	t	2	0	2	29	7	され
No.	2123	9/24	256	4176	37.15	L\$ 7665	3576	2007	45	n	3	36	£	55	25	258
е <u></u>	12:59/12	12:09	232 920	12:36 grit	12:36 92.15	65:2	13:04/02.81	13:24 9299	名主	K	Z Z	25:5	T. C.	专工	5:26	2.27
z ass	9	9		7		8	8	60	61	0	0	0	0	2	increasing -transform-	parameter parameter
ž	~	~	Аченнямаруюрую	C.	(~)	Th. All languages	d	W	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	N	(1)	abma i;	ce	M	**************	d
Speed	6	,	0	3%	3	99	K	C	e e e	3	0	(2)		69	3	73
temp	7	J	<u>u</u>	2	2	23	25.00	v,			S	N	Ŋ	2	7 20	7

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	3.5	0 0 0 0 0 0 0 0 0	8018118
	* STATE CODE	*SPS PROJECT II	*DATE
1000	Sheet 21	LTPP Traffic Data	WIM System Test Truck Records 3 of 5

E-F space														
D-E space	9	4)	0	<u></u>	Ť	t o	アナ	O F	4.0	7				
C-D space	322	33.7	326	22	23.0	& 7.7. 7.7.	32.4	32.9	32.9	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7				
B-C space	75	3	3	さず	53	E. S.	5	9- 5-	43	3				
A-B space	9.8	Z 70	8.0	5	たこ	0)	い <u>。</u>	5.3	0.0	5				
@NW	2,25	25.6	9.10	22.2	74.2	200	さま	7.27	è	去				
Axle F weight														
Axle E weight.	62/63	8778 1831	01/66	57kg	767	3	d E	7/84	Call	The state of the s				
Axle D weight.	24/26	64/18	45/1/2	E9/53	82.7%	5456	25/8h		がから	25ch	`			
Axle C weight.	200	28/20	M	52/52		12	4	20	大が	55				
Axle B weight.	750	2000	3/12	363	200	100	49/62	SC/LC	15/ BLSC	200				
Axle A weight.	56/58	(%)	3/2	5/27	25	25/20	25	75/15	53/25	E E				
WIM Speed	77	(2)	N E	to Lo	62	63	68	99	25	(100				
Record No.	15:22 259	352	030	36	4	607	486	586	263	Ser				
Time	75:3	05	95	5:50	n Ü	1C:16 479	<u>©</u>	785 74:31	李道	\$ 2				
Pass		4	스	9	ā	2	ā	5	and particular manufactures	2				
Truck	\mathcal{C}_{2}		d	(1)	, y surfront	d	(1)	gygagestus,	d	(^)				
Radar Speed	C)	S	63	19	63	69	83	Co	た	2				
Pvmt temp	いさ		23.5	222	2	7	3	A Summer	7	2				

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* STATE_CODE 3 5	T ID	* DATE R 19/08
Sheet 21	LTPP Traffic Data	WIM System Test Truck Records

E-F space									\(\))		\				
D-E space	らず	03	j J	, constant	0_	0.5							ا است	3	3-	.crifore
C-D space	7.8	32.7	32.3	33	32.7	Ä	(8	32.7	8	33.
B-C space	<i>J</i>	۳ خ	3	0	5.5	2							ナ	かさ	3	(Y)
A-B space	Š	<u>v</u>	0. 10.	2	<i>©</i> .	ð. N							2	Ø.00	ナ	4.0
MV9	かに	68.3	12	2.8	6.0	Ç							なさ	879	7.7	691
Axle F weight											,		B			
Axle E weight.	28	202	2/2	200	(4)	W SEL							200	10/20	龙	82/20
Axle D weight.	18/2	200	B.	1479 1879	13/27 12/27	M		(Y			\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	43/2	22/22	750
Axle C weight.	\$ C S	74	52/23	N.	24/8	200		1003/45					15 N	24/2	75/75	\$5/78
Axle B weight.	18	27-63	E9/15	23/N	67	SI)			A SEE SEE	5	19/8	2/52	19/5	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$
Axle A weight.	200	53/53	No so	56/56	19/3	01/0		00 4×100			J.		M5/85	63/60	958	18 82 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
Speed	G	99	6	79	83	89						3	7.9	et	9	Q
Record No.	22	3448	Š	ZZZY	2726	AR							99	<u>0</u>	ang graphi	B
Time	51.72	8:26	8:26	30.00	(S:S)	8:33							かが	2:46	3	<u>S</u> : S
Pass	distantata =	, parent Marine	water state of the	H	Cf	d		me		N	No.			M.	- Mo	and was
Truck		И	<i>on</i>	этназими	H	3		phia		Z	de			c	a	photocolongs
Radar Speed	6	99	Ç.	M	8	0	\ \{\bar{\}}				R			er e	9	t
Pvmt temp	0	8	&	\(\frac{1}{2}\)	S. E.	\$	Ş	\$		is.	B	300	g	4	2	00. 100

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LTPP Traffic Data	*SPS PROJECT_ID	
WIM System Test Truck Records	* DATE	19103

E-F space													
D-E space	40	Ť	3	0 3	9 5								
C-D space	32.9	22.2	Si Si	378	22.4								
B-C space	j	りた	J	かった	ナ ナ								
A-B space	<u>0</u>	17 17	5	600	5.7.86								
@NM	3	52.5	2.90	66.8	り に に に に に に に に に に に に に								
Axle F weight													
Axle E weight.	2000	15/2st	84,25	CH2				:					
Axle D weight.	The Co	25/23	W/cz		2/8	i							
Axte C weight.	875	56/57	21/18		200 100 100 100 100								
Axle B weight.	18	63/55	8	80/26	5%3								
Axle A weight.	85/09	365	5/56	63/10	65/2								
WIM Speed	60	27	0	2	72								
Record No.	6°5	<u>&</u>	20	475	325								
Time	7:0	<u>*</u>	7:0	<u>5</u>	· ? <u>2</u>								
Pass	7	7	0	h	Ŋ		85) 1						
Truck	d	~		ς-b	CO				:				:
Radar Speed	99	60	B	47	d								
Pvmt temp	1000	700 N	<u>8</u> 2.5	570	100 S								

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Sheet 21	LTPP Traffic Data	WIM System Test Truck Records / of 2.

E-F space																	
D-E space	,	9 3-	3	in the second	03	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		0.5	9. 3	75	3-	4:0		9	and the second		
C-D space	33.3	328	32.3	33.0	32.9	27.25	8.2	32.9	27.2	(A) (V)	32.6	3		32.0	32.2	83.0	
B-C space	t	2	7	J.	7	2 10	3	n t	J.	ナチ	63	<i>₹</i>		S	23	3	
A-B space	2	<u>0</u>	3.6	- J.	9	<u>5</u>	2	6)	2.6	(M)	6,00	5	\	6.9	9.0	7.	
@AVM	K	67.3	0250	78.7	7.60	Ñ	12	S	S.C.	K	2.50	き 以		-i	r V	83	
Axle F weight	\$																
Axle E weight.	12/2	30	65.158	200	32.32	D ST	18	30	安女	22	15 July 10 Jul	Sie		34	SE	851	
Axle D weight.	22/28	To the second	100 M	2000	(5/65	EX.	10/8	200	27/58	2/18	J. J	28/28		48/2	76/2	2000	
Axle C weight.	3/68	81/2	35/45	851 778	18/78	63/6	648	34/64	62/20	22	200	25/2	\ \a\	8	587	21/2 1/22	
Axle B weight.	98/8	82 f.	79/ES	738	18/18	19/25	78.	13/52 K	18785	808/80	The said	79/6	N/ H7/	35		163/25	187
Axle A weight.	52	0758	25/59	179g	25/20	35/0	57/56	60/59	53/58	9/49	S	0/5	N. N.	01/2/2	W.	C5/22	25/
Speed	3	Û	E	19	83	89	6 Jun	25	B	99	899	3	\ <u>\</u>	89	72	70	'
Record No.	43)	です	3	545	547	17/ 12/ 13	100	299	603	27.6	ナナの	5		9991	120	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
Time	<u></u>	<u> </u>	2	C	700	7:30	S. S	25.2	30.21	13:08	0.00	Š		92:21	3:36	Ę.	
Pass	v	W	Ø	Comment			Ø	Ø	8	24	K)	67		0	9	0	
Track	,	cb	ev	по маментарура	H	(7)	, pp. (r) (r) (r).	CP	77	**************************************	d	~		C\$	(4)	منىدومېيى.	
Radar	6	Ŋ	0	4	89	87	2	なり	d C	K	%	Co		89	H	Q	
Pvmt temp	10.0E	13.5	5,5		Land Same	agains. maninime mount	Jun-	and paid	J	128.5	N.	128.5	\$	23.5	13 13	KZ	

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7 %		0 0 0 0	000 - 00 - 00
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Sheet 21	1 TPP Traffic Data	THE COLUMN TABLE TO SEE THE CO	WIM System 1 est 1 ruck Records λ of λ

E-F space														
D-E space	<u>ب</u> ئ	<u></u>	- Line	9	er en		in	0	-mar	9	3			
C-D space	32.3	32.3	33.0	32.7	32.5	33.2	32.8	37.6	S S S S S S S S S S S S S S S S S S S	32.0	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7			
B-C space	5	₩ 7	すず	t e	ج څ	ナチ	2.3	き	Ť	C	ty			
A-B space	67	2) N)	2.0	<u>80</u>	200	7	87	N N	J.	<i>a</i> ′ <i>a</i> ′ ∞	<u>ā</u>			
GVW	(77	7.4	なか	6.39	20.00	8美	ij	25.5	60	68.0	7.0%			
Axle F weight														
Axle E weight.	25	58/22	76	63/1/20	R	180	282	100	76/	12/20	50/61			
Axle D weight.	200	200	25/5	18 SEL	120	182	200	260	58/	55	63/2)	**		
Axle C weight.	8	2000	173 A	7 11/62	30	E Le	81/13	S. S	76/24	87.8	58/2			
Axle B weight.	78/	N So	6C/h3	8	200	78/	1/8	2463	188	78/28	29/25			
Axle A weight.	200	S. S. S.	19/19	53/23	35/28	52/22	85/19	53/56	2/24	55/25	28 28			
WIM Speed	75	49	62	50	7	0	a	ŧ	79	(2)	77			
Record No.	25	195	25	[323	325	9th 25:41	子名手	17:53/750	(25)	1578	579			
Tme	2	[4:03	4	S	S	产	の主	17.59	(2:36 57)	222	97:5			
Pass		,		S	4	<u>d</u>	Ū	<u> </u>	Ø	<u>÷</u>	t	媊		
Truck	d	(\)	المعادون والمعادد المعادد المع	C.C	W		G	U	Annygh	B	W	White the state of		
Radar Speed	l 1		B	is a	2	0		상		S	2			
Pvmt	85	18.5	2	Ŋ	J	3	Co	3	Cont.	Z	7			

Recorded by MARK Z

Checked by

B

Calibration Worksheet

Calibration Iteration Date 8/19/08

Beginning factors:

Speed Point (mph)	Name	Left Sensor 1/3	Right Sensor 2 / 4
Overall			
Front Axle	(
Distance	distance (cm)	2.74	
1-(55)	88 KDY	3760	2997
2-((20)	96 Koh	3691	2942
3-(\(\) ()	105 koh	3549	2829
4-(10)	112 Xph	3694	2944
5-(75)	120 404	3623	2888

Site: __350500____

Errors:

	Speed Point				
	1 ()	2()	3 (45)	4 (10)	5 (75)
F/A			-2.7	-1,8	-1,7
Tandem			-5.8	-5.3	-4.9
GVW			-52	-3.0	-4.3

Adjustments:

•	Raise	Lower	Percentage
Overall			
Front Axle			
Speed Point 1			
Speed Point 2			
Speed Point 3			5. H
Speed Point 4	\boxtimes		3.3
Speed Point 5			Ч.5

End factors:

Speed Point (mph)	Name	Left Sensor 1/3	Right Sensor 2 / 4
Overall			
Front Axle			
Distance	distance (cm)	272	
1-(55)		3760	2997
2-((4)		3691	2942
3-(65)		3742	2982
4-(70)		3816	30 4 \$
5-(75)		3788	3019

TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

August 18, 2008

STATE: New Mexico

SHRP ID: 350500

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Photo 6 - 35_0500_Truck_2_Tractor_08_18_08.jpg	
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Photo 9 - 35_0500_Truck_2_Suspension_2_08_18_08.jpg	6
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 $Photo\ 1\ -\ 35_0500_Truck_1_Tractor_08_18_08.jpg$



Photo 2 - 35_0500_Truck_1_Trailer_08_18_08.jpg



Photo 3 - 35_0500_Truck_1_Suspension_1_08_18_08.jpg



Photo 4 - 35_0500_Truck_1_Suspension_2_08_18_08.jpg



 $Photo\ 5\ -\ 35_0500_Truck_1_Suspension_3_08_18_08.jpg$



Photo 6 - 35_0500_Truck_2_Tractor_08_18_08.jpg



 $Photo\ 7\ \hbox{--}\ 35_0500_Truck_2_Trailer_08_18_08.jpg$



Photo 8 - 35_0500_Truck_2_Suspension_1_08_18_08.jpg



Photo 9 - 35_0500_Truck_2_Suspension_2_08_18_08.jpg



Photo 10 - 35_0500_Truck_2_Suspension_3_08_18_08.jpg



Photo 11 - 35_0500_Truck_3_Tractor_08_18_08.jpg



Photo 12 - 35_0500_Truck_3_Trailer_08_18_08.jpg



Photo 13 - 35_0500_Truck_3_Suspension_1_08_18_08.jpg



Photo 14 - 35_0500_Truck_3_Suspension_2_08_18_08.jpg



 $Photo~15-35_0500_Truck_3_Suspension_3_08_18_08.jpg$

ETG LTPP CLASS SCHEME, MOD 3

Axle 1 Weight Min *						2.5				2.5	3.5	3,5			2.5	3.5	3.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross Weight Min-Max		0.10-3.00	1.00-7.99	1.00-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12,00-19,99	12.00 >	20.00 >	1.00-11.99	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20,00 >	1,00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00>	20.00 >
Spacing 8																														3.00-45.00
Spacing 7																7,777				The second secon									3.00-45.00	3.00-45.00
Spacing 6	77718								312.00						***************************************													3.00-45.00	3.00-45.00	3.00-45.00
Spacing 5						700000000000000000000000000000000000000																				2.50-10.99	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 4																			1.00-11.99	1.00-11.99	2.50-6.30	2.50-11.99	12.00-27.00	2.50-6.30	11.00-26.00	2.50-11.99	6.00-24.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3			7,000,000										1.00-11.99	1.00-11.99	1.00-20.00	2.50-12.99	13.00-50.00	2.50-20.00	1.00-11.99	1.00-25.00	2.50-6.29	6.30-65.00	6.30-50.00	2.50-6.30	6.00-20.00	6.10-50.00	11.00-26.00	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 2							6.00-25.00	6.00-25.00	3.00-7.00	6.30-30,00	2.50-6.29	11.00-45.00	6.00-30.00	6.00-30.00	6.30-40.00	2.50-6.29	2.50-6.29	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 1		1.00-5.99	6,00-10,10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6.00-26.00	10.11-23.09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00
No. Axles		7	2	7	2	7	3	3	æ	33	e	3	4	4	4	4	4	4	ĸ	\$	S	w	\$	5	5	9	9	<u>r</u>	x	6
Vehicle Type	1	Motorcycle	Passenger Car	Other (Pickup/Van)	Bus	2D Single Unit	Car w/1 Axle Trailer	Other w/ I Axle Trailer	Bus	2D w/ 1 Axie Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 3SI	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/ 3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's
Class			7	60	4	S	7	6	4	'n	9	∞	7	3	S	-	%	×	3	w		6	6	6	=	10	12	13	13	13

Spacings in feet Weights in kips (Lbs/1000)
* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

New Mexico SPS-5 (Lane 1)

Calibration Factors for Sensor #1

Validation Visit	August 19, 2008	<u>Installation</u>	May 15,2008
		<u>Calibration</u>	
Distance	272	Distance	274
88 kph	3760	88 kph	3760
96 kph	3691	96 kph	3691
105 kph	3742	105 kph	3549
112 kph	3816	112 kph	3694
120 kph	3788	120 kph	3623

Calibration Factors for Sensor #2

Validation Visit	August 19, 2008	<u>Installation</u>	May 15,2008
	_	<u>Calibration</u>	•
Distance		Distance	
88 kph	2997	88 kph	2997
96 kph	2942	96 kph	2942
105kph	2982	105 kph	2829
112 kph	3041	112 kph	2944
120 kph	3019	120 kph	2888